

IN THE SPECIFICATION

Please delete the entire paragraph on page 5 beginning at line 3.

Please amend the first full paragraph beginning on page 6, line 5, as follows:

--In a further embodiment the coil 1 is not energized continuously during the ~~clamping process~~ simulation of a haptical stop, but is clocked by a pulse generator PG by means of pulse width modulation (PWM). The PWM pattern is characterized by its frequency f and its duty cycle d . The frequency f then lies above the haptically relevant range (> 1 kHz). Such a range also facilitates the detection of the direction of rotation because a torque applied to the rotary control leads to more pronounced microstep movements, as a result of which the sensitivity of the entire arrangement increases owing to the high-pass filter HF.--

Please insert the following paragraph before the first full paragraph on page 6, line 5:

--In a further embodiment, the rotor 12 can also be soft-magnetic and thus form the magnetic return. In this case, the return 2a may be dispensed with, while furthermore the desired shear effect is produced only at the outside of the rotor 12. However, the gap 5 to be magnetized is then shorter. The rotor section 12 (in the instances described above) may alternatively be constructed as an external rotor. This means that the fluid gap 5 will be situated radially outside the stator section 2 carrying the armature winding 7.--